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## Key Elements for Initiating a Robotics-Oriented Platform

Heterogeneous embedded platforms, Ubuntu OS & industrial cameras



## Three Key Elements for Initiating Robotics-Oriented Platforms

What comes to your mind when you think about robots? A tinny mechanical voice chanting "Danger, Danger!" and waving its tube-like metal arms? Two anthropomorphic eyes on a display imitating human facial expressions? How about a steel exoskeleton with glowing red eyes from a famous tech-noir series?

Robots have developed with AI and become ubiquitous in commerce, entertainment and industrial automation. Illustratively, a study by Businesswire indicates that the market revenue for AGVs and AMRs is expected to reach US\$13.2 billion by 2026 with a growth rate of around 35%<sup>1</sup>. Despite this, finding suitable hardware and computing platforms compatible with diverse signal receivers (e.g. cameras, vibration sensors, and motion controllers) and capable of initiating robotics-oriented applications can be timeconsuming and confusing for developers.

Reducing the material sourcing efforts required of a product team necessitates exploring the three critical issues in the development of industrial robotics applications.

- 1. Categories of cameras suitable for robotics applications and their selection standards
- 2. Hardware platforms certified by Ubuntu offering guarantees to AloT developers
- 3. Advantech's latest high-performance x86 platforms, AloT device management software, and embedded design-in services

<sup>1</sup> Source: https://www.businesswire.com/news/home/20210115005190/en/Global-Mobile-Robots-AGV-AMR-Market-Expected-to-Reach-14B-by-2026---The-New-Normal-in-Our-Day-to-Day-Operational-Activities---ResearchAndMarkets.com

### Designed for AI & Robotics Applications



State-of-the-art in Heterogeneous Computing

CPU, GPU, xPU parallel computing with highbandwidth architectures



Time Deterministic & Low Latency

Wired TSN, I3C, CAN/-FD, FuSa & WiFi-6E & 5G with roaming ability



Industrial-Grade Manufacturing Quality

Small footprint with rugged design & production



Embedded Linux OS & Ubuntu Certificate

Certified Ubuntu AloT devices & Yocto BSP for diverse scenarios



MIO-2375

MIO-5375

### Selecting a suitable camera interface

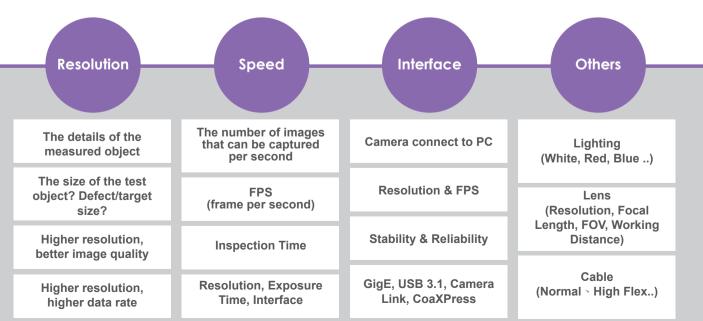
Choosing a camera that meets the needs of a specific robot requires an understanding of the four most prevalent camera interfaces — GigE, USB3.2, CameraLink, and CoaXPress.

GigE is the most common transfer interface used by industrial cameras. It is compliant with various specifications and supports plug-and-play capabilities. GigE may be advantageous because it supports long transfer distances (up to 100 meters). However, GigE is limited by lower bandwidth (at approximately 100MB/s) when compared to other transfer interfaces.

The second type is USB3.2. It supports up to 380MB/s, transfer rates (approximately 4 x the bandwidth of GigE), but has a shorter transfer distance of approximately (5 meters).

Alternatively, CameraLink provides a third option. It is superior to GigE and USB3.2 as it can reach up to 850MB/s with a standard transfer distance of 10 meters. However, CameraLink must be paired with an image capture card and camera. The fourth type is CoaXPress, also known as the CXP12 interface. CXP12 can be used with diverse interfaces (Micro BNC or HD BNC), and offers the highest industrial interface transfer volume (1500 MB/s) with 40 meter transfer distances.

Camera resolution and frame rate correspond with selecting and pairing camera interfaces. Developers should consider that higher resolutions will result in better image quality and sharper detail, but will also increase the transfer times required during data flow. Different transfer interfaces have different frame rates according to their bandwidth. Consider the following example: imagine two 25MP resolution cameras; one with a CoaXPress interface and the other with a GigE interface. The camera with GigE enables four images to be transferred per second. Conversely, the camera with CoaXPress will transfer approximately 60 images per second.



### **Check Points for Camera Selection**

Other factors that affect image quality include:

- The availability of light impacts image quality. Cameras must increase exposure time in low light conditions. This will impact transfer speed, increase noise distortion, and result in lower frame rates. Similarly, the wavelength and angle of different light sources can also affect image quality.
- Camera resolution must be paired with appropriate lens' resolutions to ensure image quality.
- 3. The lens' focal length influences ideal image capture range.
- 4. Different cable grades can affect image quality and transfer stability.

For example, automated optical inspection devices (AOI) require cameras capable of capturing tiny defects at high speeds. This necessitates using high-resolution, high-frame rate cameras with 12 megapixel CoaXPress interfaces and anti-winding cables for optimal performance. Cameras used in robotic arms often encounter slow movement speeds where images are taken from a stationary state. This means that GigE interface cameras with anti-winding cables are good option. The size of the objects intended to be photographed may also influence the choice of camera and interface.

3D imaging technologies are also adopted widely in intelligent automation. There are three commonly-applied types:

- Structured light. This principle refers to the projection of a unique light pattern onto an object. Cameras are then used to image capture the code of this unique light pattern. This code is compared to the original image before trigonometric calculations are used to find 3D coordinates which is suitable for 3D automated optical inspection (AOI) applications.
- 2. Active/passive 3D vision. This principle exploits parallax differences using two or more cameras that capture an object. After image capture, trigonometric calculations determine the distance from the detected object which is suitable for robotic arms that pick up and place objects.
- 3. Time of flight. This principle measures distance using the light's time of flight and is suitable in large work areas (larger than 10 meters). It offers slightly poorer depth and accuracy when compared to the two methods listed above, and is therefore more suitable for logistics and AMRs. Likewise, its resistance to infrared interference and IP67-rated camera shells make it suitable for outdoor/harsh-environment applications.

					Coal Press ClP-12		
Bandwidth Max in MB/S	100MB/s	600MB/s	1200MB/s	380MB/s	1500MB/s (One channel)	850MB/s	
Cable Length	100m	100m	55m(Cat6) 100m(Cat6A)	5m	40m	,	
Speed in 25MP Camera (IMX530/540)	4fps	24fps	48fps	15fps	4fps (in 4 channel)	34fps	
Multi Camera	•••			•			
CPU Loading	9			$\mathbf{C}$	•	•	
Cost	\$	\$	\$	\$	\$\$	\$\$\$	

### **Common Interfaces Comparison**

# What is the Ubuntu certificate and why does it matter?

AloT edge devices, like autonomous mobile robots (AMR), consist of multiple single board computers connected with different signal receivers (e.g. cameras, Wi-Fi cards, and motion controllers). Consequently, updating their OS regularly is crucial in ensuring device functionality.

The stock OS shipped with hardware from factories may endure unexpected vulnerabilities and defects; and require repair. Using an open and objective software security test indicator, such as Common Vulnerabilities Exposures (CVE), enables users to address vulnerabilities via downloads verified by professional OS companies. Canonical, the publisher of Ubuntu, has a designated team responsible for publishing/repairing vulnerabilities on CVE. Users can also utilize Ubuntu Security Notices (USN), a testing tool that quickly identifies patched vulnerabilities. USN also checks which versions have patches, and whether security is needed for machines currently in use.

Ubuntu also uses the Canonical Driver Test Suite (CDTS) to deliver a set of tests to OEMs, ODMs, and IHVs for use in prototyping hardware and drivers. This suite includes over a hundred test items that ensure that hardware can run

Ubuntu out-of-the-box. In addition, Ubuntu regularly releases security patches that are re-verified on certified machines to confirm that bugs have been fixed. The Long Term Support (LTS) program secures a maintenance cycle of up to 10 years. These commitments apply to ROS/ROS 2 platforms as well.

Ubuntu OS contains various AI software development kits (SDK) and a comprehensive software development ecosystem. This functionality is bolstered by close partnerships cloud services — including Azure, AWS, and Oracle. Users can utilize these services directly to train their AI models.

Canonical also verifies Advantech's latest hardware platforms regularly. Doing so ensures customers receive a direct, boot-up experience that save engineers resources when verifying compatibility between operating systems and hardware. Likewise, selecting Ubuntu certified machines for development applications offers assurances in upgrade and maintenance, post-sales update services, and cloud resource integration.

### **Benefits for Acquiring Ubuntu Certificate**



10 Year shield trio



IoT gateways on ubuntu

Safety & reliability



IoT constant updates





Ultra-reliable updates





Embedded Linux Source: Canonical

# Embedded Single Board Computer (ESBC) for Robotic Applications

Recent research regarding the development trends of industrial and mobile robotics devices indicates that hardware computing platforms are moving in the following directions:

- 1. From traditional serial computing towards heterogeneous computing and parallel computing: Data sources such as images, video streams, voices, and the sensor fusion mechanism have been included for realizing the era of AloT. Traditional CPUs provided a general-purpose computing performance that is suitable for serial computing. However, to process the abovementioned data sources with deep learning and Al inference using algorithms such as DNN, CNN, and RNN, parallel computing proved to be more advantageous. Thanks to the latest technology, developers now can leverage SoC built-in NPU and VPU or extended GPU, FPGA, and xPU via a highbandwidth interface to achieve workload consolidation.
- 2. Time deterministic computing and low-latency network connections have become essential: The use of low-latency network connections improves computing performance by ensuring that more actions or data can be processed within a single time unit. AloT equipment interacts closely with its environment. The use of low-latency network technologies such as TSN (Time Sensitive Networking), Wi-Fi 6/6E, and 5G enables devices to perform real-time computing in their environments and respond accordingly. This greatly expands the service range of robotic equipment.
- 3. Increased demand for industrial-grade design and manufacturing: The operation environment for robots has shifted from indoor (e.g. factory floors and largescale warehousing logistics) to outdoor scenarios (e.g. grocery deliveries or community safety inspections.) Maintaining reliability necessitates outdoor-oriented

robots capable of operating in rugged environments. Such solutions require water-/shock-resistant designs with wide-range temperature tolerances. Advantech's embedded single board computers (ESBC) are adapted to wide operating temperature ranges (-40 ~ 85 °C) and are treated with conformal coating during the manufacturing process. These products all passed IPC-A-610 Class 3 standards manufacturing criteria for improved durability and stability.

4. Ubuntu OS and Ubuntu certified AloT devices have gone mainstream: A 2020 HackerEarth Developer Survey<sup>2</sup> indicates that 66% of experienced developers and 69% of students prefer Ubuntu over comparable Linux distributions. Indeed, Ubuntu OS is very popular with AloT device developers due to its ease of use, excellent security, and robust ecosystem support. Advantech has invested resources in Ubuntu OS certification for embedded single board computers (ESBC) before shipping them from the factory. This saves customers' time when testing software/hardware compatibility during the early periods of a project.

Through Ubuntu certification program, AloT devices with Ubuntu certification receive a tri-weekly verification service on the released patch. This provides peace of mind of knowing that your AloT devices remain secure and updated.

The Advantech ESBC team offers a full range of highperformance Ubuntu certified embedded platforms that fulfill the needs of intelligent robotics applications and the trends discussed in this report. Our highly-integrated solutions are designed to reduce their users' time-to-market while providing the reliability needed to enhance AI development.

<sup>&</sup>lt;sup>2</sup> Source: https://recruit-c7ff.kxcdn.com/recruit/wp-content/uploads/2020/05/ he-developer-survey-2020.pdf

### Advantech Domain-Focused Embedded SBC Platforms









#### **MIO-2364**

#### Pico-ITX 32EU Compact Sized and Low Power Design

- Next Gen. Intel<sup>®</sup> Atom up to 8 E-Cores, TDP=6~15W
- Intel<sup>®</sup> UHD GFx Gen12 up to 32EUs for AI Inference
- 2.5GbE opt. PoE/PD module for camera input
- M.2 E-key & B/M-key for WiFi/BT, 5G/ LTE and storage



#### **MIO-4370**

#### 4"SBC 32EU Scalable & Flexible AI Computing Platform

- 12<sup>th</sup> Gen. Intel<sup>®</sup> Core i9/i7/i5/i3 Celeron, TDP=35W
- Scalable AI from built-in Xe GFx to M.2
  PCIe x4 Gen.5
- 3 M.2 includes dual M.2 2280 for NVMe storage & AI expansions
- Dual 2.5GbE w/ TSN for real-time, 6 USB, 2 UART, CAN



#### **MIO-2375**

#### Pico-ITX 96EU Light-Weight AI Platform

- 11<sup>th</sup> Gen. Intel<sup>®</sup> Core i7/i5/i3/Celeron, TDP=15W
- Onboard dual channel LPDDR4x
  maximum AI capacity
- Sufficient sensor interfaces via 2 GbE, 4 USB, 2 RS-232/422/485
- standard 0~60°C and extended -40~85°C variants



#### **MIO-5375**

#### 3.5"SBC 96EU Maximum Built-in AI with Rich Expansions

- 11<sup>th</sup> Gen. Intel<sup>®</sup> Core i7/i5/i3/Celeron, TDP=15/28W
- Rich I/O ports include 2 GbE, Type-C, 6 USB, 4 UARTs, CAN, 4 Displays
- 3 M.2 expansion via E-key, B-key, M-key PClex4 Gen.4
- DC-in 12~24V, standard 0~60°C and extended -40~85°C variants



<sup>10</sup> 114-6



### **MIO-5377**

#### 3.5"SBC 96EU Hybrid-core design with 8x Camera & 9x Sensor I/O

- 12<sup>th</sup> Gen. Intel<sup>®</sup> Core Hybrid i7/i5/i3/ Celeron, TDP=15/28W
- Rich I/O ports include 2 GbE, USB4, Type-C, 4 UARTs, 3 I2C, 2 CAN
- 4 individual displays include LVDS, HDMI2.0, DP1.4, USB4, Type-C up to 8K
- 3 M.2 via E/B/M-key for WiFi/BT, 5G/ LTE, NVMe, DC-in 12~24V

#### **EPC-C301**

#### Fanless BOX PC Compact Embedded System with Rich I/O Ports

- 8<sup>th</sup> Gen. Intel<sup>®</sup> Core i7/i5 Quad Core, TDP=15W
- Rich I/O ports include 4 GbE, 8 USB, 4 UART, 2 CAN isolation
- 4 expansions: M.2 E-key, B-key, M-key, miniPCle for wireless & Al
- Extended operating temperature: -20~60°C

# ESBC Product Selection

	Preliminary MIO-2364	MIO-2375	MIO-5375	
Form Factor	Pico-ITX	Pico-ITX	3.5" SBC	
Processor	Next Gen. Intel Atom	11 <sup>th</sup> Gen. Intel Core/Celeron	11 <sup>th</sup> Gen. Intel Core/Celeron	
Cores/ Threads	8C/8T	4C/8T	4C/8T	
Memory	DDR5 1-CH 32GB	Onboard LPDDR4x 32GB	DDR4 2-CH 64GB	
Display	LVDS, HDMI1.4	eDP1.4/MIPI-DSI, DP1.4	LVDS/eDP, HDMI2.0, DP1.4, Type-C	
Expansion	M.2 E-Key & B/M-Key	M.2 E-Key & B/M-Key	3x M.2 E/B/M-Key	
Power Input	DC-in 12V, ATX/AT Mode	DC-in 12V, ATX/AT Mode	DC-in 12~24V, ATX/AT Mode	
I/O Ports	GbE, 4 USB, 2 UART, GPIO, SATA, Audio, SMBus, TPM	2 GbE, 4 USB, 2 UART, GPIO, SATA, Audio, I2C, TPM	2 GbE, 6 USB, Type-C, CANBus, 4 UART, GPIO, SATA, Audio, I2C, TPM	
Thermal	Fanless Heatsink	Active Cooler	Fanless Heatsink for TDP=15W Active Cooler for TDP=28W	
Operating Temperature	0~60°C	0~60°C & -40~85°C	0~60°C & -40~85°C	
Dimensions	100 x 72mm	100 x 72mm	146 x 102mm	
Software	Windows, Ubuntu, Yocto	Windows, Ubuntu, Yocto	Windows, Ubuntu	

### **ESBC Product Selection**

	MIO-5377	MIO-4370	EPC-C301		
Form Factor	3.5" SBC	4" SBC	Embedded Fanless PC		
Processor	12 <sup>th</sup> Gen. Intel Core/Celeron	12 <sup>th</sup> Gen. Intel Core/Celeron	8 <sup>th</sup> Gen. Intel Core i7/i5		
Cores/ Threads	4P+8E/16	8P+8E/24T	4C/8T		
Memory	DDR5 2-CH 64GB	DDR5 1-CH 32GB	DDR4 2-CH 32GB		
Display	LVDS, HDMI2.0, DP1.4, Type-C, USB4	eDP1.4, 2x HDMI1.2	HDMI1.4, DP1.2		
Expansion	3x M.2 E/B/M-Key	M.2 E-Key, 2x M-Key	3x M.2 E/B/M-Key, mPCle		
Power Input	DC-in 12~24V, ATX/AT Mode	DC-in 12V, ATX/AT Mode	DC-in 12V, ATX Mode		
I/O Ports	2 GbE, USB4, 6 USB, Type-C, CANBus, 4 UART, GPIO, SATA, Audio, I2C, TPM	2 GbE, 6 USB, CANBus, 2 UART, GPIO, Audio, I2C, TPM	4 GbE, 8 USB, 2 CANBus, 4 UART, GPIO, Audio		
Thermal	Fanless Heatsink for TDP=15W Active Cooler for TDP=28W	Active Cooler	Fanless Design		
Operating Temperature	0~60°C & -40~85°C	0~60°C	-20~60°C w/0.7m/s Air Flow		
Dimensions	146 x 102mm	165 x 115mm	170 x 118 x 70 mm		
Software	Windows, Ubuntu	Windows, Ubuntu	Windows, Ubuntu, Yocto		

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### **Embedded Peripheral Solutions**

AIW-163BR	AIW-210XU-001	SQR-SD5N	SQF-S8B 650
Form Factor M.2 2230 A-E key	Form Factor M.2 2242 B-key	DDR DDR5	Connect Type NGFF B&M Key
Wireless Standard 802.11ax + BT5.2	GPS Type Hardware Standalone	DIMM Type SODIMM	Flash Type 3D TLC
Chipset RTL 8852BE	Signal Protocol USB	Pin Number 262pin	<b>Capacity</b> 64GB ~ 2TB
Signal Protocol WiFi: PCIe BT: USB	Chipset NEO-M9N	Frequence(MHz) 4800	Transfer Mode SATA III (Up to 6Gb/s)
Antenna 2 x MHF4 connectors	Operating Temperature -40°C ~ 85°C (-40°F ~ 185°F)	Capacity 8/16/32GB	Max. Power Consumption Read: 1.5 W, Write:1.75 W
Operating Voltage DC 3.3V	<b>RF Receiver Type</b> GPS module, multi-GNSS (GPS/BeiDou/Galileo/ GLONASS/QZSS/SBAS)	Voltage 1.1V	Sustained R/W Performance (*) up to 550/ 520 MB/sec
Temperature Range 0∼70 °C (32∼158°F)	<b>GPS Acquisition</b> Cold Start: 24s / Hot Start: 2s	Operating Temperature 0 ∼ 85 °C	Operating Temperature Commercial Temperature: 0 to +70 °C Minus Temperature: -20 to +85 °C Extended Temperature: -40 to +85 °C
<b>Dimensions</b> 22 x 30 x 2.2 mm 0.86x1.18x0.086 in	GPS Accuracy Aided Start: 2s	DeviceOn/ SQ Manager Developing	Shock Resistance 1,500 G, peak / 0.5 ms
Security WPA/WPA2/WPA3	GPS Sensitivity Tracking & Navigation: -167 dBm Reacquisition: -160 dBm Cold Start: -148 dBm		<b>Vibration Resistance</b> 20 G, peak / 80 ~ 2000 Hz
MIMO 2T2R MIMO			Dimensions (mm) 80.0 x 22.0 x 3.8
Data Rate 802.11ax: 1.2Gbps			(*) These values are for reference only; they may change according to the flash memory used.
<b>OS support</b> Windows / Linux			

### **Embedded Board Solutions**

	AIMB-218Z	EPC-U3233	SOM-6883	EPC-R7200/7300	
Form Factor	Mini-ITX Motherboard	Embedded System	COMe Compact	Embedded System	
Processor	Intel Atom x6413E	Intel <sup>®</sup> Core™ i7-8665UE	Intel <sup>®</sup> 11 <sup>th</sup> Gen Core™ I Processors	NVIDIA Jetson Family	
Cores/ Threads	4C/4T	4C/8T	4C/8T	Up to 8 CPU cores & 1024 CUDA cores	
Memory	2 Channel 260-pin DDR4 SODIMM up to 3200 MHz 2 SODIMM slots, Max. 32GB (16GB per DIMM)	1 x DDR4-2400 SO-DIMM (260-Pin) 32GB Max	2 Channel 288-pin DDR4 SODIMM up to 3200 MT/s, Max. 32GB	Up to 16GB	
Display	DP, HDMI, LVDS(eDP)	2 HDMI	VGA, LVDS, eDP(Optional), HDMI/DP	HDMI	
Expansion	1 PCle x1	M.2 M-Key 2280 M.2 E-Key 2230 M.2 B-Key 3042	5 PClex1 (Up to 6 by option)	M.2 KeyB, KeyE and UIO40-Express	
Power Input	DC-in 12V	DC-in 12V	Vin: 8.5V ~ 20V VSB: 4.75V ~ 5.25 V	DC-in 9-24V	
I/O Ports	x2 GbE x3 USB 3.2 Gen 1 x5 USB 2.0 x1 RS-232 x5 RS-232/422/485	x2 GbE x2 USB 3.2 Gen1 x2 USB 2.0 x4 COM x2 GPIO	x1 GbE x4 USB 3.2 Gen2 x8 USB 2.0 x2 2-wire UART x2 SATA 3.0 x8 GPIO x1 I2C x1 TPM (Optional)	x2 GbE x2 USB 3.2 Gen 1 x2 RS-232 x1 CAN * more I/O configurations can be extended by UIO40-Express	
Thermal	Fanless	Fanless	Heat-spreader and Smei- heatsink with Fan, QFCS	Fanless	
Operating Temperature	-20°C ~ 70°C	0°C ~ 50°C	-40°C ~ 85 °C (Depends on CPU)	-20°C ~ 70°C	
Dimensions	170 mm x 170 mm	180 x 116.7 x 66mm	95 x 95 mm	152 x 138 x 42 mm	
Software	SUSI API WISE-DeviceOn Windows Linux Ubuntu	SUSI API WISE-DeviceOn Windows Linux Ubuntu	WISE-DeviceOn Windows	Linux Ubuntu WISE-DeviceOn	

# Worldwide



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Norl	dwide (	Offices							
Asia	Pacific		Asia Paci	fic	Europe		Americas		
Taiwar			Japan		Netherlands		North America		
Toll Fr		0800-777-111	Toll Free	0800-500-1055	Eindhoven	31-40-267-7000	Toll Free	1 9	388-576-9668
		s 886-2-2792-7818	Tokyo	81-3-6802-1021	Breda		Cincinnati		513-742-8895
Taich		886-4-2372-5058	Osaka	81-6-6267-1887	Біеца	31-76-523-3100	Milpitas		08-519-3898
Kaoh		886-7-392-3600	Nagoya	81-0800-500-1055	Cormonu		Irvine		49-420-2500
	J		Nogata	81-949-22-2890	Germany	00000 0400 0000	Ottown		315-433-5100
China			0		Toll Free	00800-2426-8080/	Chicago		88-576-9668
Toll F	ree	800-810-0345	Korea		Munich Düsseldorf	49-89-12599-0			
Beijir		86-10-6298-4346	Toll Free	080-363-9494/5	Dusseidoll	49-2103-97-855-0	Brazil		
Shan	0	86-21-3632-1616	Seoul	82-2-3660-9255	France		Toll Free	080	00-770-5355
Sher		86-755-8212-4222				00 4 4440 4000	São Paulo		-11-5592-5367
Cher	qdu	86-28-8545-0198	Singapore		Paris	33-1-4119-4666	Guo Fuuro		
	Kong	852-2720-5118	Singapore	65-6442-1000	14-h-		Mexico		
	Ŭ				Italy			1.0	00 407 0445
			Malaysia		Milan	39-02-9544-961	Toll Free		300-467-2415
			Kuala Lumpur	60-3-7725-4188			Mexico City	52-	-55-6275-2777
			Penang	60-4-537-9188	UK				
			5		Newcastle	44-0-191-262-4844	Middle Ea	oct a	nd Africa
			Thailand		London	44-0-870-493-1433			
			Bangkok	66-02-2488306-9			Israel	072	2-2410527
			Daligkok	00-02-2400300-3	Spain		Turkey	90-	-212-222-0422
			Vietnam		Madrid	34-91-668-86-76	Turkey-Bursa	90-	-224-413-3134
			Hanoi	84-24-3399-1155					
			Hochiminh	84-28-3836-5856	Sweden				
				01 20 0000 0000	Stockholm	46-0-864-60-500			
			Indonesia						
			Jakarta	62-21-751-1939	Poland				
			Jakalla	02-21-731-1939	Warsaw	48-22-31-51-100			
			Australia						
			Toll Free	1300-308-531	Russia				
			Melbourne	61-3-9797-0100	Moscow	8-800-555-01-50			
			Melbourne	0.001010100	St. Petersburg	8-812-332-57-27			
			India			8-921-575-13-59			
			Bangalore	91-94-4839-7300					
			Pune	91-94-2260-2349	Czech Republic				
					Ústí nad Orlicí	420-465-524-421			
					Ireland				
						252 04 702444			
					Galway	353-91-792444			



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